

# TEST REPORT EN 61851-24 Electric vehicle conductive charging system – Digital communication between a d.c. EV charging station and an electric vehicle for control of d.c. charging

Report Number:	SHES240601275201-03
Date of issue:	2024-07-03
Total number of pages	49
Name of Testing Laboratory preparing the Report:	SGS-CSTC Standards Technical Services (Shanghai) Co., Ltd. 588 West Jindu Road, Xinqiao, Songjiang, 201612 Shanghai, China.
Applicant's name:	Shanghai SUNNIC New Energy Technology Co., Ltd
Address:	6/F, building C3, district C, Changyang chuanggu, 1687 Changyang Road, Yangpu District, Shanghai, China
Test specification:	
Standard:	EN 61851-24:2014/AC:2015 for use in conjunction with EN 61851-23:2014/AC:2016-06
Test procedure:	SGS-CSTC
Non-standard test method:	N/A
Test item description:	EV DC Charging Station
Trade Mark:	🔇 နပဂဂၢင
Manufacturer :	Shanghai SUNNIC New Energy Technology Co., Ltd 6/F, building C3, district C, Changyang chuanggu, 1687 Changyang Road, Yangpu District, Shanghai, China
Model/Type reference:	See Page 8 to 14
Ratings:	See Page 8 to 14



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Resp	Responsible Testing Laboratory (as applicable), testing procedure and testing location(s):				
$\boxtimes$	Testing Laboratory:	SGS-CSTC Standards Technical Services (Shanghai) Co., Ltd.			
Testi	ng location/ address:	588 West Jindu Road, Xinqiao, Songjiang, 201612 Shanghai, China.			
Test	ed by (name, function, signature):	Jazz Yan			
Appr	oved by (name, function, signature):	Vince Cheng			
	Testing procedure: CTF Stage 1:				
Testi	ng location/ address:				
Test	ed by (name, function, signature):				
Appr	oved by (name, function, signature):				
	Testing procedure: CTF Stage 2:				
Testi	ng location/ address:				
Test	ed by (name + signature)				
Witn	essed by (name, function, signature) .:				
Appr	oved by (name, function, signature):				
	Testing procedure: CTF Stage 3:				
	Testing procedure: CTF Stage 4:				
Testi	ng location/ address:				
Test	ed by (name, function, signature):				
Witn	essed by (name, function, signature) .:				
Appr	oved by (name, function, signature):				
Supe	ervised by (name, function, signature) :				



List of Attachments (including a total number of pages in each attachment): See SGS Report No.: SHES240601275201-01

## Summary of testing:

This report was based on original test report no. SHES240200338904-03, issued on 2024-07-02, only with following changes:

-- change the applicant and manufacturer to Shanghai SUNNIC New Energy Technology Co., Ltd 6/F, building C3, district C, Changyang chuanggu, 1687 Changyang Road, Yangpu District, Shanghai, China

-- change the trademark to

## 🔇 sunnic

-- change referred Report Number from SHES240200338904-01 to SHES240601275201-01

-- change the model number to SKBDC240KE-xx(x), SKBDC180KE-xx(x), SKBDC160KE-xx(x), SKBDC150KE-xx(x), SKBDC120KE-xx(x), SKBDC80KE-xx(x), SKBDC60KE-xx(x), SKBDC50KE-xx(x) which are identical with the previous models no. YLUXD240KE-xx(x), YLUXD180KE-xx(x), YLUXD160KE-xx(x), YLUXD150KE-xx(x), YLUXD150KE-xx(x), YLUXD120KE-xx(x), YLUXD80KE-xx(x), YLUXD60KE-xx(x), YLUXD50KE-xx(x) in the original report and only different on the models no., see below for details

Report No.	SHES240601275201-03	SHES240200338904-03	
	SKBDC240KE-xx(x)	YLUXD240KE-xx(x)	
	SKBDC180KE-xx(x)	YLUXD180KE-xx(x)	
	SKBDC160KE-xx(x)	YLUXD160KE-xx(x)	
Model No.	SKBDC150KE-xx(x)	YLUXD150KE-xx(x)	
	SKBDC120KE-xx(x)	YLUXD120KE-xx(x)	
	SKBDC80KE-xx(x)	YLUXD80KE-xx(x)	
	SKBDC60KE-xx(x)	YLUXD60KE-xx(x)	
	SKBDC50KE-xx(x)	YLUXD50KE-xx(x)	

Note:

1. "xx(x)" in sample model can be:

"xx" can be 01, 02, 05, 06, 13 or 14.

"(x)" only can be A.

2. For example, SKBDC240KE-01 is identical with YLUXD240KE-01, SKBDC240KE-01(A) is identical with YLUXD240KE-01(A). Based on the above two examples, the models correspond one by one.

After inspection, no additional tests were considered necessary.

SGS	Dage 4 of 40	Depart No. SHES240604275204.02
I	Page 4 of 49	Report No. SHES240601275201-03
Tests performed (name of test and test clause):	SGS	i <b>ng location:</b> -CSTC Standards Technical Services
Full test.	(Sha	nghai) Co., Ltd.
		88 West Jindu Road, Xinqiao, Songjiang, 12 Shanghai, China
Summary of compliance with National	Differences (Lis	t of countries addressed):
UK Differences		

The product fulfils the requirements of EN 61851-24:2014, EN 61851-24:2014/AC:2015 for use in conjunction with EN 61851-23:2014/AC:2016-06 which are EQV with IEC 61851-24:2014, IEC 61851-24:2014/COR1:2015 for use in conjunction with IEC 61851-23:2014/COR1:2016.



## Copy of marking plate:

See SGS Report No.: SHES240601275201-01



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Test item particulars:	
Equipment mobility:	☐ movable ☐ hand-held ☐ transportable ⊠ stationary ☐ for building-in ☐ direct plug-in
Connection to the mains:	<ul> <li>pluggable equipment type A type B</li> <li>permanent connection</li> <li>detachable power supply cord</li> <li>non-detachable power supply cord</li> <li>not directly connected to the mains</li> </ul>
EV charging modes:	<ul> <li>Mode 1 charging</li> <li>Mode 2 charging</li> <li>Mode 3 charging</li> <li>Mode 4 charging</li> </ul>
Type of EV connection:	<ul> <li>□ Case A</li> <li>□ Case B</li> <li>⊠ Case C</li> </ul>
Access location:	<ul> <li>operator accessible</li> <li>service access area</li> <li>restricted access location</li> </ul>
Over voltage category (OVC)	□ OVC I □ OVC II □ OVC III □ OVC IV □ other:
Mains supply tolerance (%) or absolute mains supply values	±10%
Tested for IT power systems:	🗌 Yes 🛛 No
IT testing, phase-phase voltage (V)	N/A
Class of equipment:	⊠ Class I
Considered current rating (A)	See model list
Pollution degree (PD)	🗌 PD 1 🔄 PD 2 🖾 PD 3
IP protection class	IP54
Altitude during operation (m)	2000
Altitude of test laboratory (m)	<200m
Mass of equipment (kg)	<500kg

# SGS

Possible test case verdicts:

- test case does not apply to the test object:	N/A
- test object does meet the requirement:	P (Pass)
- test object does not meet the requirement:	F (Fail)
Testing:	
Date of receipt of test item:	2024-01-10(Original date)
Date (s) of performance of tests:	2024-01-11 to 2024-01-31(Original date)

## General remarks:

"(See Enclosure #)" refers to additional information appended to the report.

"(See appended table)" refers to a table appended to the report.

## Throughout this report a $\boxtimes$ comma / $\square$ point is used as the decimal separator.

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Unless otherwise stated the results shown in this test report refer only to the sample(s) tested and such sample(s) are retained for 30 days only.

## Manufacturer's Declaration:

The application for obtaining a Test Certificate includes more than one factory location and a declaration from the Manufacturer stating that the sample(s) submitted for evaluation is (are) representative of the products from each factory has been provided	<ul> <li>☐ Yes</li> <li>☑ Not applicable</li> </ul>

## When differences exist; they shall be identified in the General product information section.

Name and address of factory (ies):	Winline Technology (Changshu) Co., Ltd.
	Buildings 10-3 and 12-3, Jiadi Industrial Park, No. 1150, Dongnan Avenue, Changshu City, Suzhou City, Jiangsu Province, 215500, P. R. China



IC/POS

IC(RFID)

card

IC(RFID)

card

POS

POS

## General product information:

1. The DUT (Equipment Under Test) used for EV Battery charging. The DC EV charger could provide IEC CCS2 connector and CHAdeMO connector for mode 4 DC charging.

2. The EUT can operate under 2000m altitude. The operation environment temperature is -30 to 50°C.

3. The EUT is Class I appliance with protection degree IP54 and IK10 for indoor/outdoor use.

4. The charging system is comprised of SPD, circuit breaker, power modules, control board, communication board, RCD, emergency stop switch, one or two vehicle connectors(CHAdeMO or CCS2) with cable (case C connection), touch screen, contactors, etc. Live parts separated from the earthed metal frame inside enclosure by B.I. And live parts separated from accessible plastic enclosure by R.I. or D.I. The touch screen on enclosure is supplied by SELV output voltage of switch mode power supply.

5. CCS2 connector of system C and CHAdeMO connector of system A can be parallel loop, they can charge simultaneously. In case of dual connectors charging, the maximum power of single CCS connector is half of the rate power of identical EV charger, and the maximum power of single CHAdeMO connector is 62,5 kW or half of the rate power of the identical EV charger.

6. There are eight series in the model list: 240kw series, 180kw series, 160kw series, 150kw series, 120kw series, 80kw series, 60kw series and 50kw series. The difference between these series is charging modules quantity and the size of DC EV charger. 240kw series and 180kw series has 6 pcs charging modules. 160kw series, 150kw series and 120kw series has 4 pcs charging modules. 80kw series, 60kw series and 50kw series has 2 pcs charging modules. For 160kw series, 80kw series, 50kw series models, power is limited by software.

Size of 240kw series and 180kw series is 850 \* 2000 \* 800 mm<sup>3</sup>.

Size of 160kw series, 150kw series, 120kw series is 850 \* 2000 \* 610 mm<sup>3</sup>.

Size of 80kw series, 60kw series and 50kw series is 800 \* 1800 \* 500 mm<sup>3</sup>.

7. When two charging guns are charging simultaneously, each module can only be connected to one charging.

Model list				
Model	Input Rating	Rated Output Rating	Balancer connector hanging	
SKBDC240KE-01			Yes	
SKBDC240KE-01A	240kw series: 400VAC±10%, 3P+N+PE	CCS2(Connector A): Max.240kW Max.1000VDC/Max.300A	No	
SKBDC240KE-02	50/60Hz Max. 368 A	CCS2(Connector B): Max.240kW Max.1000VDC/Max.300A	Yes	
SKBDC240KE-02A			No	

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Model	Input Rating	Rated Output Rating	Balancer connector hanging	IC/POS
SKBDC240KE-05		CCS2(Connector A): Max.240kW Max.1000VDC/Max.300A	Yes	IC(RFID) card
SKBDC240KE-05A			No	IC(RFID) card
SKBDC240KE-06	240kw series: 400VAC±10%, 3P+N+PE	CHAdeMO(Connector B): Max.62.5kW/Max.500VDC/ Max.125A	Yes	POS
SKBDC240KE-06A	50/60Hz Max. 368 A		No	POS
SKBDC240KE-13		CCS2(Connector A): Max.240kW Max.1000VDC/Max.300A	Yes	IC(RFID) card
SKBDC240KE-13A			No	IC(RFID) card
SKBDC180KE-01		CCS2(Connector A): Max.180kW Max.1000VDC/Max.300A CCS2(B): Max.180kW Max.1000VDC/Max.300A	Yes	IC(RFID) card
SKBDC180KE-01A			No	IC(RFID) card
SKBDC180KE-02			Yes	POS
SKBDC180KE-02A	180kw series: 400VAC±10%, — 3P+N+PE		No	POS
SKBDC180KE-05	50/60Hz Max. 276 A	CCS2(Connector A): Max.180kW Max.1000VDC/Max.300A CHAdeMO(Connector B): Max.62.5kW/Max.500VDC/ Max.125A	Yes	IC(RFID) card
SKBDC180KE-05A			No	IC(RFID) card
SKBDC180KE-06			Yes	POS
SKBDC180KE-06A			No	POS



Model	Input Rating	Rated Output Rating	Balancer connector hanging	IC/POS
SKBDC180KE-13	180kw series: 400VAC±10%, – 3P+N+PE 50/60Hz Max. 276 A	CCS2(Connector A): Max.180kW	Yes	IC(RFID) card
SKBDC180KE-13A		Max.1000VDC/Max.300A	No	IC(RFID) card
SKBDC160KE-01			Yes	IC(RFID) card
SKBDC160KE-01A		CCS2(Connector A): Max.160kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC160KE-02		CCS2(Connector B): Max.160kW Max.1000VDC/Max.200A	Yes	POS
SKBDC160KE-02A			No	POS
SKBDC160KE-05	160kw series: 400VAC±10%,	CCS2(Connector A): Max.160kWMax.1000VDC/ Max.200A CHAdeMO(Connector B): Max.62.5kW/Max.500VDC/ Max.125A CCS2(Connector A): Max.160kW Max.1000VDC/Max.200A	Yes	IC(RFID) card
SKBDC160KE-05A	- 3P+N+PE 50/60Hz Max. 246 A		No	IC(RFID) card
SKBDC160KE-06			Yes	POS
SKBDC160KE-06A			No	POS
SKBDC160KE-13			Yes	IC(RFID) card
SKBDC160KE-13A			No	IC(RFID) card
SKBDC150KE-01	150kw series: 400VAC±10%,	CCS2(Connector A): Max.150kW Max.1000VDC/Max.200A CCS2(Connector B): Max.150kW Max.1000VDC/Max.200A	Yes	IC(RFID) card
SKBDC150KE-01A			No	IC(RFID) card



Model	Input Rating	Rated Output Rating	Balancer connector hanging	IC/POS
SKBDC150KE-02		CCS2(Connector A): Max.150kW Max.1000VDC/Max.200A	Yes	POS
SKBDC150KE-02A		CCS2(Connector B): Max.150kW Max.1000VDC/Max.200A	No	POS
SKBDC150KE-05			Yes	IC(RFID) card
SKBDC150KE-05A	150kw series: 400VAC±10%, 3P+N+PE	CCS2(Connector A): Max.150kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC150KE-06	50/60Hz Max. 230 A	CHAdeMO(Connector B): Max.62.5kW/Max.500VDC/ Max.125A	Yes	POS
SKBDC150KE-06A			No	POS
SKBDC150KE-13		CCS2(Connector A): Max.150kW Max.1000VDC/Max.200A	Yes	IC(RFID) card
SKBDC150KE-13A			No	IC(RFID) card
SKBDC120KE-01		CCS2(A): Max.120kW Max.1000VDC/Max.200A CCS2(B): Max.120kW Max.1000VDC/Max.200A CCS2(Connector A): Max.120kW Max.1000VDC/Max.200A CHAdeMO(Connector B): Max.62.5kW Max.500VDC/Max.125A	Yes	IC(RFID) card
SKBDC120KE-01A			No	IC(RFID) card
SKBDC120KE-02	120kw series: 400VAC±10%, 3P+N+PE		Yes	POS
SKBDC120KE-02A	50/60Hz Max. 184 A		No	POS
SKBDC120KE-05			Yes	IC(RFID) card
SKBDC120KE-05A			No	IC(RFID) card



Model	Input Rating	Rated Output Rating	Balancer connector hanging	IC/POS
SKBDC120KE-06		CCS2(Connector A): Max.120kW Max.1000VDC/Max.200A	Yes	POS
SKBDC120KE-06A	120kw series: 400VAC±10%, 3P+N+PE	CHAdeMO(Connector B): Max.62.5kW Max.500VDC/Max.125A	No	POS
SKBDC120KE-13	50/60Hz Max. 184 A	CCS2(Connector A): Max.120kW	Yes	IC(RFID) card
SKBDC120KE-13A		Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC80KE-01			Yes	IC(RFID) card
SKBDC80KE-01A		CCS2(Connector A): Max.80kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC80KE-02		CCS2(Connector B): Max.80kW Max.1000VDC/Max.200A	Yes	POS
SKBDC80KE-02A			No	POS
SKBDC80KE-05	80kw series: 400VAC±10%,		Yes	IC(RFID) card
SKBDC80KE-05A		CCS2(Connector A): Max.80kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC80KE-06		CHAdeMO(Connector B): Max.62.5kW Max.500VDC/Max.125A	Yes	POS
SKBDC80KE-06A			No	POS
SKBDC80KE-13		CCS2(Connector A): Max.80kW	Yes	IC(RFID) card
SKBDC80KE-13A		Max.80kW Max.1000VDC/Max.200A	No	IC(RFID) card



Model	Input Rating	Rated Output Rating	Balancer connector hanging	IC/POS
SKBDC80KE-14	80kw series: 400VAC±10%, - 3P+N+PE	400VAC±10%, CCS2(Connector A):		POS
SKBDC80KE-14A	50/60Hz Max. 123 A	Max.1000VDC/Max.200A	No	POS
SKBDC60KE-01			Yes	IC(RFID) card
SKBDC60KE-01A		CCS2(Connector A): Max.60kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC60KE-02		CCS2(Connector B): Max.60kW Max.1000VDC/Max.200A	Yes	POS
SKBDC60KE-02A			No	POS
SKBDC60KE-05			Yes	IC(RFID) card
SKBDC60KE-05A	60kw series: 400VAC±10%,	CCS2(Connector A): Max.60kW Max.1000VDC/Max.200A	No	IC(RFID) card
SKBDC60KE-06	- 3P+N+PE 50/60Hz Max. 92 A	CHAdeMO(Connector B): Max.60kW Max.500VDC/Max.125A	Yes	POS
SKBDC60KE-06A			No	POS
SKBDC60KE-13			Yes	IC(RFID) card
SKBDC60KE-13A		CCS2(Connector A): Max.60kW	No	IC(RFID) card
SKBDC60KE-14		Max.1000VDC/Max.200A	Yes	POS
SKBDC60KE-14A			No	POS



4	50kw series:	CCS2(Connector A): Max.50kW Max.1000VDC/Max.167A CCS2(Connector B): Max.50kW Max.1000VDC/Max.167A	Yes No Yes No Yes	IC(RFID) card IC(RFID) card POS POS IC(RFID) card
SKBDC50KE-02 SKBDC50KE-02A SKBDC50KE-05 SKBDC50KE-05A	50kw series:	Max.50kW Max.1000VDC/Max.167A CCS2(Connector B): Max.50kW Max.1000VDC/Max.167A	Yes	POS POS IC(RFID)
SKBDC50KE-02A SKBDC50KE-05 SKBDC50KE-05A	50kw series:	Max.50kW Max.1000VDC/Max.167A	No	POS IC(RFID)
SKBDC50KE-05 SKBDC50KE-05A	50kw series:			IC(RFID)
SKBDC50KE-05A	50kw series:		Yes	
4	50kw series:			I
	50kw series: 400VAC±10%, 3P+N+PE 50/60Hz Max. 77 A	CCS2(Connector A): Max.50kW Max.1000VDC/Max.167A CHAdeMO(Connector B): Max.50kW Max.500VDC/Max.125A	No	IC(RFID) card
SKBDC50KE-06			Yes	POS
SKBDC50KE-06A			No	POS
SKBDC50KE-13			Yes	IC(RFID) card
SKBDC50KE-13A		CCS2(Connector A): Max.50kW	No	IC(RFID) card
SKBDC50KE-14		Max.1000VDC/Max.167A	Yes	POS
SKBDC50KE-14A			No	POS



## EN 61851-24

	EN 61851-24						
Clause	Requirement + Test	Result - Remark	Verdict				
4	SYSTEM CONFIGURATION						
	102.2 of IEC 61851-23.	The model with CHAdeMO charging connector comply with System AA. The model with IEC CCS charging connector comply with System CC.	Ρ				
5	DIGITAL COMMUNICATION ARCHITECTURE						
	Two digital communication architectures are used:		Р				
		For the model with CHAdeMO charging connector	Ρ				
		For the model with CCS charging connector	Ρ				
6	CHARGING CONTROL PROCESS						
	The charging control process is in accordance with 102.5 of IEC 61851-23.		Ρ				
7	OVERVIEW OF CHARGING CONTROL		Р				
	The digital communication of d.c. charging control covered by this standard is as shown in Figure 1.		Ρ				
8	EXCHANGED INFORMATION FOR D.C. CHARGING CONTROL						
	Information which is exchanged between a d.c. EV charging station and a vehicle during the charging process according to IEC 61851-23.	(see appended Table 1)	Ρ				
	The information in Table 1 is common to all systems described in Annexes A, B and C.		Ρ				
	Each information listed in Table 1 is defined as a parameter in each annex.		Ρ				
	Each system may need additional parameters, and these parameters are defined in each annex.		Ρ				
ANNEX A	DIGITAL COMMUNICATION FOR CONTROL OF D.	C. EV CHARGING SYSTEM A	Р				
A.1	General		Р				
	The specification of digital communication for control of the d.c EV charging station of system A (in this annex, referred to as "system A station" or "station") as specified in Annex AA of IEC 61851-23. More detailed information on system A is defined in JIS/TSD0007.		Ρ				
A.2	Digital communication actions during charging co	ntrol process	Р				
	The communication actions and parameters according to the charging control process as defined in Table 103 of IEC 61851-23 are shown in Table A.1.	(see appended Table A.1)	Ρ				
. <u> </u>							



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	EN 61851-24		
Clause	Requirement + Test	Result - Remark	Verdict
	The parameters for digital communication of d.c. charging control are exchanged according to the sequence diagram as shown in Figure A.1.		Р
A.4	Parameter definition		Р
	The definition of parameters during d.c. charging control process are shown in Table A.2.	(see appended Table A.2)	Р
A.5	Physical/data link layer	·	Р
A.5.1	Specifications		Р
	The physical/data link layer specifications are shown in Table A.3.	(see appended Table A.3)	Р
A.5.2	Communication circuit		Р
	The CAN communication circuit is established to exchange parameters, i.e. voltage, current, status flags, and fault flags, which are necessary for the charging control.		Р
	<ul> <li>Terminating resistor</li> </ul>		Р
	1:1 communication is assumed.		
	The vehicle and the d.c. EV charging station are equipped with terminating resistors.		Р
	<ul> <li>Noise filter</li> <li>The vehicle and the d.c. EV charging station are</li> </ul>		Р
	equipped with noise filters to reduce the conducted noise of the common mode and differential mode.		
	– Twisted-pair line		Р
	Twisted pair line are utilized as the communication line that links the d.c. EV charging station with the vehicle so as to reduce differential mode noise.		
	- CAN transceiver		Р
	CAN transceiver is equipped to send and receive CAN communication data.		
	The CAN-bus circuit is established independently for d.c. charging, as shown in Figure A.2.		Р
A.5.3	Transmission		Р
	Data frames are transmitted in ascending order of ID number specified in Table A.2.		Р
	The data frames are continuously transmitted at 100 ms (± 10 %) interval through the charging process.		Р
	Interval duration (ms):		
A.5.4	Reception		Р
	When the vehicle or the d.c. EV charging station receives data frames from the other party, the received frames are echoed.		Р
	Furthermore, the received error frames are destroyed.		Р



## EN 61851-24

	LIN 01001-24						
Clause	Requirement + Test	Result - Remark	Verdict				
A.5.5	CAN communication						
	Figure A.3 shows the basic specifications related to the dedicated CAN communication between the vehicle and the d.c. EV charging station.		Р				
ANNEX B	DIGITAL COMMUNICATION FOR CONTROL OF D.	C. EV CHARGING SYSTEM B	N/A				
B.1	General		N/A				
	The specification of d.c. charging control digital communication for the d.c EV charging station of system B (in this annex, referred to as "System B station" or "charger") as specified in Annex BB of IEC 61851-23.		N/A				
B.2	Digital communication of d.c. charging control						
	The parameters for digital communication of d.c. charging control are exchanged according to the sequence diagram as shown in Figure B.1.		N/A				
B.3	Digital communication actions during charging control process						
	The communication actions and parameters during d.c. charging control process are shown in Table B.1. (see appended Table B.1)						
B.4	Parameter definition		N/A				
	The definition of parameters during d.c. charging control process are shown in Tables B.2, B.3, B.4, B.5 and B.6.	(see appended Tables B.2 , B.3, B.4, B.5,and B.6)	N/A				
B.5	Physical/data link layer		N/A				
	The physical/data link layer specifications are shown in Table B.7.	(see appended Table B.7)	N/A				
	The physical/data link layer refers to SAE J1939-11 and SAE J1939-21.		N/A				
	The application layer refers to GB/T 27930.		N/A				



	EN 61851-24						
Clause	Requirement + Test	Result - Remark	Verdict				
ANNEX C	DIGITAL COMMUNICATION FOR CONTROL OF D.C. CHARGING SYSTEM C (COMBINED SYSTEM)						
C.1	General						
	The digital communication for the d.c EV charging station of system C as specified in Annex CC of IEC 61851-23 is defined in the following standards: DIN SPEC 70121, ISO/IEC 15118-1, ISO/IEC 15118-2 and ISO/IEC 15118-3.	For the model with IEC CCS charging connector DIN SPEC 70121	Ρ				
	The following SAE specifications can also be used as information: SAE J2836/2™, SAE J2847/2, SAE J2931/1 and SAE J2931/4.		Р				
	Systems implementing these specifications incorporate the following features:		Р				
	• security concept including encryption, signing, key management, etc.		Р				
	<ul> <li>robust PLC-based communications,</li> </ul>		Р				
	automatic address assigning and association,		Р				
	IPv6-based communications,		Р				
	compressed XML messages,		Р				
	client-server approach,		Р				
	<ul> <li>safety concept including cable check, welding detection, etc.</li> </ul>		Р				
	extension concept for added-value services.		Р				
C.2	Required exchange parameters		Р				
	The parameters to be exchanged for d.c. charging control are shown in Table C.1, corresponding to Table 1.	(see appended Table C.1)	Р				
	Additional parameters can be found in DIN SPEC 70121 and ISO/IEC 15118-2.		Р				



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Clause Requirement + Test

Result - Remark

8	TABLE 1: Exchanged in	formation for d.c. charging control			Р
No.	Information Description		Relevant requirement in IEC 61851-23 (unless specified as IEC 61851-1)	Other remarks	Verdict
a-1	Current request for the controlled current charging (CCC) system	Exchange of current value requested by EV	6.4.3.101, DC supply		Р
a-2	Voltage request for the controlled voltage charging (CVC) system	Exchange of voltage value requested by EV	6.4.3.101, DC supply		Ρ
			6.4.3.101, DC supply		Ρ
a-3	Maximum rated voltage of d.c. EV charging station				Ρ
			6.4.3.107, Protection against overvoltage at the battery		Ρ
a-4	Maximum rated current of d.c. EV	Exchange of maximum rated current	6.4.3.101, DC supply for EV		Р
a-4	charging station	value of d.c. EV charging station	6.4.3.105, Compatibility assessment		Ρ
b-1	Communication protocol	Exchange of software version of a charging system	6.4.3.105, Compatibility assessment		Ρ
b-2	Maximum voltage limit of EV	Exchange of maximum voltage limit value of vehicle.	6.4.3.105, Compatibility assessment		Ρ
b-3	EV minimum current limit, only for the controlled voltage charging (CVC) system	not defined yet	6.4.3.105, Compatibility assessment		Р
с	Insulation test result	Exchange of the result of insulation test before charging	6.4.3.106, Insulation test before charging		Ρ



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		EN 61851-2	24	
Clause	Requirement + Test		Result - Remark	Verdict
		- If insulation test fails, a signal is sent that charging is not allowed.	6.4.3.106, Insulation test before charging	Р
d	Short circuit test before charging	Exchange of information on short circuit test before charging	6.4.3.110, Short circuit test before charging	Р
е	Charging stopped by user	Exchange of information on charge stop command by the user of d.c. EV charging station	6.4.3.111, User initiated shutdown	Р
f	EVSE real time available load current (optional) EVSE real time available load current for demand mar Required for system providir function.		6.4.4.2 (of IEC 61851-1), Detection/adjustment of the real time available load current of EVSE	Р
		Detection of loss of digital communication	9.4, Breaking capacity	Р
g	Loss of digital communication	- If a receiver does not get information expected to receive within time out period, it is considered as loss of digital communication.		Р
		Notification of zero current confirmed	102.5, Charging control process and state	Р
h-1	Zero current confirmed	- Station informs EV that low current condition has been met (to allow connector unlocking)	102.5, Charging control process and state	Р



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# EN 61851-24 EN 61851-24 Clause Requirement + Test Result - Remark Verdict h-2 Welding detection Exchange of information on the whole process of welding detection 102.5, Charging control process and state P Supplementary information: Supplementary information: Exchange of information on the whole process and state P



Page 22 of 49 Report No. SHES240601275201-03 EN 61851-24 Clause Requirement + Test Result - Remark Verdict TABLE A.1 – Communication actions and parameters during d.c. charging control process between system A station Ρ **ANNEX A.2** and vehicle Parameter Charging High level action at **Digital communication** control State system level <sup>a</sup> From d.c. EV action stage From vehicle Other remarks Verdict charging station DC-A Vehicle unconnected None N/A N/A N/A N/A DC-B1 Connector plugged in None N/A N/A Wake up of DCCCF and (default CAN) N/A None None VCCF DC-B1 Preparation for digital Communication data (default CAN) (default CAN) Ρ initialization communication Handshaking Initialization - Control protocol number Control protocol - Rated capacity of number battery - Maximum batterv Communication - Available output DC-B1 → established, parameters Exchange of charging voltage voltage Ρ - Maximum charging control parameters - Available output DC-B2 exchanged, and compatibility checked current time - Target battery - Battery incompatibility voltage - Vehicle charging enabled DC-B2 → - Vehicle connector Notification of connector Charge preparati Connector locked Р None DC-B3 locked status lock Insulation test for d.c. Charging system Р DC-B3 None None power line malfunction



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Clause	Rec	quirement + Test		F	Verdict	
	DC-B3	Pre-charge (depending on the system architecture)	N/A	N/A	N/A	N/A
	DC-C or DC-D	Vehicle side contactors closed	Notification of vehicle main contactor closed status	None	None	Р
Energy transfer	DC-C or DC-D	Charging by current demand (for CCC)	Notification of request value of charging current (or voltage)	<ul> <li>Station status</li> <li>Output voltage</li> <li>Output current</li> <li>Remaining charging time</li> <li>Station malfunction</li> <li>Charging system malfunction</li> </ul>	Output voltage- Charging currentOutput currentrequestRemaining charging- Charging systemnefaultStation malfunction- Vehicle shift leverCharging systemposition	
	DC-C or DC-D	Charging by voltage demand (for CVC)	N/A	N/A	N/A	N/A
	DC-C,(D) → DC-B'1	Current suppression	Request of energy transfer shut-off	<ul> <li>Station status</li> <li>Charging stop contro</li> <li>Output voltage</li> <li>Output current</li> </ul>	I Vehicle charging enabled	P
	DC-B'1	Zero current confirmed	Notification of energy transfer shut-off	- Station status - Charging system malfunction	-	P
Shutdown	DC-B'1 → DC-B'2	Welding detection (by vehicle)	-	None	None	N/A
N	DC-B'2	Vehicle side contactors open	None	None	None	N/A
	DC-B'2	DC power line voltage verification	Notification of present voltage	Output voltage	None	Р



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Requirement + Test		R	Result - Remark	Verdict
3 Connector unlocked	Notification of connector unlocked status	Vehicle connector lock	None	Р
End of charge at communication level	Terminate the digital communication	None	None	Р
Connector unplugged		N/A	N/A	N/A
1	End of charge at communication level Connector unplugged	BConnector unlockedconnector unlocked statusEnd of charge at communication levelTerminate the digital communicationConnector unplugged	Base       Connector unlocked       connector unlocked       Vehicle connector lock         Base       End of charge at communication level       Terminate the digital communication       None         Connector unplugged       N/A	Base       Connector unlocked       connector unlocked       Vehicle connector lock       None         Base       End of charge at communication level       Terminate the digital communication       None       None       Image: Connector lock       None



b-2

Page 25 of 49 Report No. SHES240601275201-03 EN 61851-24 Requirement + Test Clause Result - Remark Verdict ANNEX A.4 TABLE A.2 – Exchanged parameter during d.c. charging control process between system A station and vehicle N/A CAN ID Resoluti Data Item in ID.byte Source Verdict Parameter Content Destination update Unit Status flag on Other remarks Table 1 (bit) (range) rate The maximum voltage value at the Maximum vehicle inlet H'100.4 System A 500V ΕV Ρ terminals. at which V battery 100 ms 1 V/bit H'100.5 01F41 station the station stops voltage charging to protect the vehicle battery Rated Rated capacity of System A H'101.5 0.1 kWh capacity ΕV 100 ms kWh N/A of H'101.6 /bit station battery battery Fixed value for charging rate Constant of indication, which is 1 %/bit, charging System A H'100.6 ΕV 100 % Р the maximum % 100 ms rate station charging rate (fixed) indication (100 %) of vehicle battery Maximum Maximum charging 10 s/bit charging System A time permitted by H'101.1 ΕV (0 to FFH Ρ 100 ms s time station EV, set by 10 s 2 540 s) (set by 10 s)



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	EN 61851-24										
Clause		Requirement + Test						Result - Rema	ark		Verdict
	Maximum charging time (set by minute)	Maximum charging time permitted by EV, set by minute	H'101.2	EV	System A station	100 ms	min	-	1 min/bit (0 to 255 min)	FFH	Р
	Estimated charging time	Estimated remaining time before the end of charging calculated by EV	H'101.3	EV	System A station	100 ms	min	-	1 min/bit (0 to 254 min)	FFH	Р
b-1	Control protocol number	Software version of control protocol to which EV corresponds	H'102.0	EV	System A station	100 ms	-	-	1 /bit (0 to 255)		Р
	Target battery voltage	Targeted charging voltage at the vehicle inlet terminals	H'102.1 H'102.2	EV	System A station	100 ms	v	-	1 V/bit (0 to 600 V)	500V 01F4H	Р
a-1	Charging current- request	Current value requested by EV during charging	H'102.3	EV	System A station	100 ms	A	-	1 A/bit (0 to 255 A)		Р
	Charging rate	Charging rate of vehicle battery	H'102.6	EV	System A station	100 ms	%	-	1 %/bit (0 % to 100 %)		Р
g	Vehicle charging enabled	Status flag indicating charge permission status of EV	H'102.5(0)	EV	System A station	-	-	0: disabled 1: enabled	-	Enable 1	Р



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## EN 61851-24

					EN 6185	51-24					
Clause	Req	uirement + Test						Result - Remark			Verdict
Vehic lever positi	r	Status flag indicating the shift lever position	H'102.5(1)	EV	System A station	-	-	<b>0:</b> "Parking" position <b>1:</b> other position	P 0	Parking	Ρ
Char syste	ging em fault	Status flag indicating a malfunction caused by EV or the station, and detected by EV	H'102.5(2)	EV	System A station	-	-	<b>0:</b> normal <b>1:</b> fault	N 0	lormal	Ρ
Vehic statu		Status flag indicating the EV contactor status	H'102.5(3)	EV	System A station	-	-	0: EV contactor closed or during welding detection, 1: EV contactor open or welding detection finished			Ρ



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## EN 61851-24

					EN 618	51-24				
Clause	F	Requirement + Test						Result - Remark		Verdict
	Normal stop request before charging	Status flag indicating the request of EV to stop charging control	H'102.5(4)	EV	System A station	-	-	0: no request 1: request to stop		Р
	Battery overvoltag	Status flag indicating whether or not the vehicle battery voltage exceeds the maximum limit specified by EV	H'102.4(0)	EV	System A station	-	-	0: normal, 1: fault	Normal 0	Ρ
	Battery undervolta	Status flag indicating whether or not the vehicle battery voltage is less than the lower limit specified by EV	H'102.4(1)	EV	System A station	-	-	0: normal 1: fault	Normal 0	Р
	Battery current deviation error	Status flag indicating whether or not the output current deviates from EV requested current	H'102.4(2)	EV	System A station	-	-	0: normal 1: fault	Normal 0	Р



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## EN 61851-24

					EN 618	51-24					
Clause	R	equirement + Test					F	Result - Rema	rk		Verdict
	High batter temperatur		H'102.4(3)	EV	System A station	-	-	<b>0:</b> normal 1: fault	-	Normal 0	Ρ
	Battery voltage deviation error	Status flag indicating whether or not the vehicle battery voltage deviates from the output voltage measured by the station	H'102.4(4)	EV	System A station	-	-	0: normal, 1: fault	-	Normal 0	Ρ
h-2	EV contactor welding detection support identifier	Identifier indicating whether or not the station deals with EV contactor welding detection	H'108.0	System A station	EV	100 ms	-	0: not supporting vehicle welding detection, 1 or more: supporting vehicle welding detection	-	Supporting 01H	Ρ
a-3	Available output voltage	Maximum output voltage value at the vehicle connector terminals	H'108.1 H'108.2	System A station	EV	100 ms	V	-	1 V/bit (0 to 600 V)	500V 01F4H	Ρ



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					EN 618	51-24					
Clause	I	Requirement + Test						Result - Re	mark		Verdict
a-4	Available output current	Maximum output current value of the station	H'108.3	System A station	EV	100 ms	A	-	1 A/bit (0 to 255 A)		Р
b-2	Threshold voltage	Threshold voltage to stop the charging process in order to protect vehicle battery	H'108.4 H'108.5	System A station	EV	100 ms	V	-	1 V/bit (0 to 600 V)	500V 01F4H	Р
b-1	Control protocol number	Software version number of control protocol or charging sequences that the station deals with	H'109.0	System A station	EV	100 ms	-	-	1 / bit (0 to 255)		Р
	Output voltage	Supply voltage value of the output circuit in the station	H'109.1 H'109.2	System A station	EV	100 ms	V	-	1 V/bit (0 to 600 V)		Р
	Output current	Supply current value of the output circuit in the station	H'109.3	System A station	EV	100 ms	A	-	1 A/bit (0 to 255 A)		Р
	Remaining charging time (counted to 10 s)	before the end of	H'109.6	System A station	EV	100 ms	s	-	10 s/bit (0 to 2540 s)		Р
	Remaining charging time (counted t min)	before the end of	H'109.7	System A station	EV	100 ms	min	-	1 min/bit (0 to 255 min)		Р



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Clause	F	Requirement + Test						Result - Rema	rk		Verdict
c h-1	Station status	Status flag indicating the energy transfer from the station	H'109.5(0)	System A station	EV	100 ms	-	0: standby 1: charging	-	Charging 1	Ρ
	Station malfunctio	Status flag indicating whether or not there is a malfunction caused by the station	H'109.5(1)	System A station	EV	100 ms	-	<b>0:</b> normal, <b>1:</b> fault	-	Normal 0	Ρ
	Vehicle connector lock	Status flag indicating the electromagnetic lock status of vehicle connector	H'109.5(2)	System A station	EV	100 ms	-	0: unlocked 1: locked	-	Locked 1	Ρ
	Battery in- compatibili		H'109.5(3)	System A station	EV	100 ms	-	0: compatible 1: in compatible	-	Compatible 0	Ρ
d	Charging system malfunctio	Status flag indicating whether or not there is a problem with EV, such as improper connection	H'109.5(4)	System A station	EV	100 ms	-	0: normal 1: mal function	-	Normal 0	Ρ



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Clause	R	equirement + Test					Result - Remark	Verdict		
e	Charger sto control	Status flag indicating whether or not the station proceeds with shutdown process	H'109.5(5)	System A station	EV	100 ms	-	0: operating, 1: shutdown or stop charging	Operating 0	Ρ



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Clause	Requirement + Test	Result - Remark	Verdict

ANNEX 5.1	TABLE	A.3 – The physical/data link	layer specifications for system A		Р
				Other remarks	Verdict
		Communication protocol	ISO 11898-1 and ISO 11898-2 The extension bit (12 - 29 bit) is not used.		Р
Communication sys	stem	Transmission rate (kbps)	500	500kbps	Р
		Cycle	100 ms ± 10 %	100ms± 5%	Р
Supplementary info	ormation:		· ·		



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		EN 61851-24	4				
Clause	Requirement + Test			Result - Rem	ark		Verdict
ANNEX B.3	TABLE B.1 – Communication acti and vehicle	ons and parameters during d.c.	charging	control proces	ss between s	ystem B station	N/A
Charging control stage (process)	Digital communication action	Information	Source	Destination	Parameter cycle	Other remarks	Verdict
Handshaking	Confirm the necessary parameters	Charger recognition parameter	Charger	Vehicle	250 ms		N/A
Tianusnaking	of battery and charger.	Vehicle recognition parameter	Vehicle	Charger	250 ms		N/A
		Battery charge parameter	Vehicle	Charger	500 ms		N/A
narameter		Charger time synchronization	Charger	Vehicle	500 ms		N/A
	Exchange of charging control parameters.	Charger max/min output parameter	Charger	Vehicle	250 ms		N/A
g		Vehicle charge ready	Vehicle	Charger	250 ms		N/A
		Charger output ready	Charger	Vehicle	250 ms		N/A
		Battery charge requirement	Vehicle	Charger	50 ms		N/A
		Charger charge status	Charger	Vehicle	50 ms		N/A
	Send charging status to each	Battery charge status 1	Vehicle	Charger	250 ms		N/A
Ob a nain a lata na	other, according to the battery	Battery charge status 2	Vehicle	Charger	250 ms		N/A
Charging stage	charge level requirements sent by Vehicle; the charger adjusts the	Battery cell voltage	Vehicle	Charger	1 s		N/A
	charging process.	Battery temperature	Vehicle	Charger	1 s		N/A
		Vehicle stopping command	Vehicle	Charger	10 ms		N/A
		Charger stopping command	Charger	Vehicle	10 ms		N/A



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Clause	Requirement + Test			Result - Remark			Verdict
Charging ending	Energy transfer shut-off.	Vehicle statistic data	Vehicle	Charger	250 ms		N/A
stage	Energy transfer shut-off.	Charger statistic data	Charger	Vehicle	250 ms		N/A
Communication	Restart communication program or	Vehicle receiving error	Vehicle	Charger	250 ms		N/A
error	stop charging process.	Charger receiving error	Charger	Vehicle	250 ms		N/A
Supplementary inf	ormation:						



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Requirement + Test				Res	sult - Remark		Verdict	
TABLE B.2 – Parameters in charge	handshak	e stage f	or system B				N/A	
Parameter	M <sup>a</sup> /O <sup>b</sup>	Unit	Resolution	Status flag	Item in Table 1	Other remarks	Verdict	
Recognition result	м	-	-	0x00: unre- cognized 0xAA: re- cognized	-		N/A	
Charger number	М	-	-	-	-		N/A	
Charger/charge station location code	0	-	-	-	-		N/A	
Vehicle communication protocol version	М	-	-	-	b-1		N/A	
Battery type code	М	-	-	-	-		N/A	
Battery system rated capacity	М	Ah	0,1 Ah/bit	-	-		N/A	
Battery system rated voltage	М	V	0,1 V/bit	-	-		N/A	
Battery manufacturer code, ASCII	0	-	-	-	-		N/A	
	TABLE B.2 – Parameters in charge         Parameter         Parameter         Recognition result         Charger number         Charger number         Charger/charge station location code         Vehicle communication protocol version         Battery type code         Battery system rated capacity         Battery system rated voltage	TABLE B.2 – Parameters in charge handshakeParameterMª /ObRecognition resultMCharger numberMCharger/charge station location codeOVehicle communication protocol versionMBattery type codeMBattery system rated capacityMBattery system rated voltageM	TABLE B.2 – Parameters in charge handshake stage for ParameterParameterMª /ObUnitRecognition resultM-Charger numberM-Charger/charge station location codeO-Vehicle communication protocol versionM-Battery type codeM-Battery system rated capacityMAhBattery system rated voltageMV	TABLE B.2 – Parameters in charge handshake stage for system BParameterMª /ObUnitResolutionRecognition resultMCharger numberMCharger/charge station location codeOVehicle communication protocol versionMBattery type codeMBattery system rated capacityMAh0,1 Ah/bitBattery system rated voltageMV0,1 V/bit	TABLE B.2 – Parameters in charge handshake stage for system BParameterMª /ObUnitResolutionStatus flagRecognition resultM0x00: unre- cognized 0xAA: re- cognizedCharger numberMCharger/charge station location codeOVehicle communication protocol versionMBattery type codeMBattery system rated capacityMAh0,1 Ah/bit-Battery system rated voltageMV0,1 V/bit-	TABLE B.2 – Parameters in charge handshake stage for system BParameterMª /O <sup>b</sup> UnitResolutionStatus flagItem in Table 1Recognition resultM0x00: unre- cognized 0xAA: re- cognizedCharger numberMCharger/charge station location codeOVehicle communication protocol versionMBattery type codeMBattery system rated capacityMAh0,1 Ah/bitBattery system rated voltageMV0,1 V/bit	TABLE B.2 – Parameters in charge handshake stage for system BParameterMª /ObUnitResolutionStatus flagItem in Table 1Other remarksRecognition resultM0x00: unre- cognized0x0A: re- cognized-Charger numberMCharger/charge station location codeOVehicle communication protocol versionMBattery type codeMBattery system rated capacityMAh0,1 Ah/bitBattery system rated voltageMV0,1 V/bit	



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Clause	Requirement + Test				Re	esult - Remark		Verdict
ANNEX B.4	TABLE B.3 – Parameters in charge	parameter	<sup>·</sup> configu	ration stage fo	or system B			N/A
Information	Parameter	<b>М</b> <sup>а</sup> /О <sup>ь</sup>	Unit	Resolution	Status flag	Item in Table 1	Other remarks	Verdict
	Maximum permissible charge voltage of battery cell	М	V	0,01 V/bit	-	-		N/A
	Maximum permissible charge current	М	A	0,1 A/bit	-	-		N/A
Battery charge	Maximum permissible charge energy	М	kWh	0,1 kWh/bit	-	-		N/A
parameter	Maximum permissible charge voltage of battery system	М	V	0,1 V/bit	-	b-2		N/A
	Maximum permissible temperature	М	°C	1 °C/bit	-	-		N/A
	The initial SOC	М	%	0,1 %/bit	-	-		N/A
	Total voltage of battery system	М	V	0,1 V/bit	-	-		N/A
Charger time synchronization	Year/month/date/hour/minute/ second	0	-	-	-	-		N/A
	Maximum output voltage	М	V	0,1 V/bit	-	a-3		N/A
Charger max/min output parameter	Minimum output voltage	М	V	0,1 V/bit	-	-		N/A
	Maximum output current	М	А	0,1 A/bit	-	a-4		N/A
Vehicle charge ready	If the vehicle is ready to be charged	М	-	-	0x00: unready 0xAA: ready	-		N/A
Charger output ready	If the charger is ready to charge	м	-	-	0x00: unready 0xAA: ready	-		N/A

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Clause	Requirement + Test	Result - Remark	Verdict
<sup>a</sup> M = Mandatory <sup>b</sup> O = Optional			
Supplementary inf	ormation:		



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Clause	Requirement + Test				Re	sult - Remark		Verdict	
ANNEX B.4	TABLE B.4 – Parameters in charging stage for system B								
Information	Parameter	M <sup>a</sup> /O <sup>b</sup>	Unit	Resolution	Status flag	Item in Table 1	Other remarks	Verdict	
Battery charge	Voltage requirement	М	V	0,1 V/bit	-	a-2		N/A	
requirement	Current requirement	М	А	0,1 A/bit	-	a-1		N/A	
	Charge mode	М	-	-	-	-		N/A	
Charger charge	Output voltage	М	V	0,1 V/bit	-	-		N/A	
state	Output current	М	А	0,1 A/bit	-	h-1		N/A	
	Accumulated charge time	М	min	1 min/bit	-	-		N/A	
	Measured charge voltage	М	V	0,1 V/bit	-	-		N/A	
	Measured charge current	М	А	0,1 A/bit	-	-		N/A	
Battery charge state 1	Maximum cell voltage and corresponding battery pack number <sup>c</sup>	М	V	0,01 V/bit	-	-		N/A	
	SOC	М	%	1 %/bit	-	-		N/A	
	Estimated remainder time	М	min	1 min/bit	-	-		N/A	
	Cell number of maximum cell voltage	М	-	-	-	-		N/A	
	Maximum battery temperature	М	°C	1 °C/bit	-	-		N/A	
Battery charge state 2	Test point number of maximum temperature	М		-	-	-		N/A	
	Minimum battery temperature	М	°C	1 °C/bit	-	-		N/A	
	Test point number of minimum temperature	М	-	-	-	-		N/A	



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Clause	Requirement + Test				R	esult - Remark	Verdict
	Cell voltage over-high	М	-	-	0: normal 1: over-high	-	N/A
	Cell voltage over-low	М	-	-	0: normal 1: over-low	-	N/A
	Battery charge overcurrent	М	-	-	0: normal 1: over- current	-	N/A
	Battery temperature overhigh	М	-	-	0: normal 1: over-high	-	N/A
	Battery insulation state	М	-	-	0: normal 1: abnormal	-	N/A
	Connection state of battery output connector	М	-	-	0: normal 1: abnormal	-	N/A
	Charge permission	М	-	-	0: forbidden 1: permissior	c, d	N/A
Battery cell voltage	Voltage of each battery cell	0	V	0,01 V/bit	-	-	N/A

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t O	°C	1 °C/bit	-		N/A
					N/A
М	-	-	-	-	N/A
M	-	-	-	h-2	N/A
М	-	-	-	-	N/A
М	-	-	-	е	N/A
on M	-	-	-	-	N/A
M	-	-	-	-	N/A
	n M M M on M	n M - M - M - M - on M -	M M M on M	M         -         -         -           M         -         -         -           M         -         -         -           M         -         -         -           M         -         -         -           M         -         -         -           M         -         -         -	M         -         -         h-2           M         -         -         h-2           M         -         -         -           M         -         -         -           M         -         -         e           M         -         -         e           M         -         -         e



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Clause	Requirement + Test     Result - Remark							Verdict
ANNEX B.4	TABLE B.5 – Parameters in charge ending stage for system B							
Information	Parameter	M <sup>a</sup> /O <sup>b</sup>	Unit	Resolution	Status fla	g Item in Table 1	Other remarks	Verdict
Vehicle statistic data	The final SOC	М	%	1 % /bit	-	-		N/A
	Minimum cell voltage	М	V	0,01 V/bit	-	-		N/A
	Maximum cell voltage	М	V	0,01 V/bit	-	-		N/A
aala	Minimum battery temperature	М	°C	1 °C/bit	-	-		N/A
	Maximum battery temperature	М	°C	1 °C/bit	-	-		N/A
Charger statistic	Accumulated charge time	М	min	1 min/bit	-	-		N/A
data	Accumulated output energy	М	kWh	0,1 kWh/bit	-	-		N/A
<sup>a</sup> M = Mandatory <sup>b</sup> O = Optional								
Supplementary in	formation:							



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Clause	Requirement + Test	equirement + Test Result - Remark							
ANNEX B.4 TABLE B.6 – Error parameters for system B							N/A		
Information	Parameter	M <sup>a</sup> /O <sup>b</sup>	Unit	Resolution	Status flag	Item in Table 1	Other remarks	Verdict	
Vehicle receiving error	Receiving timeout of information from charger	м	-	-	-	g		N/A	
Charger receiving error	Receiving timeout of information from vehicle	м	-	-	-	g		N/A	
<sup>a</sup> M = Mandatory <sup>b</sup> O = Optional					·				
Supplementary inf	ormation:								

ANNEX B.5	TABLE B.7 – Physical/data lir	k layer specifications for system B		N/A	
			Other remarks	Verdict	
	Communication protocol	CAN 2,0 B, ISO 11898-1		N/A	
Communication system	Transmission rate (kbps)	250		N/A	
System	Cycle	10/50/250/500/1 000 ms ± 10 %		N/A	
Supplementary in	formation:	·			



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### EN 61851-24 Requirement + Test Clause Result - Remark Verdict ANNEX C.2 TABLE C.1 – Required exchanged parameters for d.c. charging control for system C Ρ Item in Parameter name (ISO/IEC 15118-2) Other remarks Information Verdict Table 1 EV target current is set at 150 A. Current request for the controlled CurrentDemandReq/EVTargetCurrent Р a-1 current charging (CCC) system EVTargetCurrent=1500 (3 -1) EV target voltage is set at 400 V. Voltage request for the controlled voltage CurrentDemandReq/EVTargetVoltage Ρ a-2 charging (CVC) system EVTargetVoltage=4000 (5 -1) EVSE Maximum Voltage Limit **İS** set at 1000 V. Maximum rated voltage of d.c. EV CurrentDemandRes/EVSEMaximumVoltageLimit Ρ a-3 charging station EVSEMaximumVoltageLi mit=1000 (5 -1) EVSE Maximum Current Limit iS set at 150 A. Maximum rated current of d.c. EV CurrentDemandRes/EVSEMaximumCurrentLimit Ρ a-4 charging station **EVSEMaximumCurrentLi** mit=1500 (3 -1)

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EVMaximumVoltageLimit: Multiplier:0 Unit: V

Value:1000

Р

Result - Remark V2G: < ApplicationProtocolHands hake Protocol entry #=1	Verdict
ApplicationProtocolHands hake Protocol entry #=1	
ProtocolNamespace=urn: din:70121:2012:MsgDef Version=2.0 SchemalD=1 Priority=1 Supported SchemalD(DIN)=1 Protocol entry #=2 ProtocolNamespace=urn:i so:15118:2:2013:MsgDef Version=2.0 SchemalD=2 Priority=2 Supported SchemalD(V2G)=2 V2G: Protocol=DIN(schemalD= 1) V2G:> ApplicationProtocolHands hake EVSE: state=STATE_EVSE_ISO 15118	Ρ
	Protocol=DIN(schemaID= 1) V2G:> ApplicationProtocolHands hake EVSE: state=STATE_EVSE_ISO

CurrentDemandReq/EVMaximumVoltageLimit

Maximum voltage limit of EV

b-2



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Clause		Requirement + Test	Resu	lt - Remark	Verdict
b-3		nimum current limit, only for the lled voltage charging (CVC) system	ChargeParameterDiscoveryRes / DC_EVSEChargeParameter / EVSEMinimumCurrentLimit	EVSE minimum current limit is 5A EVSEMinimumCurrentLi mit: Multiplier:-1 Unit: A Value:50	Ρ
с	Insulat	tion test result	{PowerDeliveryRes, CableCheckRes, PreCharge CurrentDemandRes, WeldingDetectionRes} / DC EVSEIsolationStatus		Ρ



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Clause		Requirement + Test	Result - Re	emark	Verdict
d	Short ci	ircuit test before charging	CableCheck{Req,Res}	CableCheckReq: DC_EVStatus: EVReady: true EVErrorCode: NO_ERROR EVRESSSOC:50 CableCheckRes: ResponseCode: FAILED DC_EVSEStatus: EVSEIsolationStatus: Invalid EVSEStatusCode: EVSE_Malfunction NotificationMaxDelay: 0 EVSENotification: None EVSEProcessing: Finished	Ρ
e	Chargir	ng stopped by user	<ul> <li>{ChargeParameterDiscoveryRes,PowerDeliveryR es, CableCheckRes, PreChargeRes, CurrentDemandRes WeldingDetectionRes} / DC_EVSEStatus / EVSEStatu EVSE_Shutdown</li> <li>{ChargeParameterDiscoveryRes, PowerDeliveryRes, CableCheckRes, PreChargeRes, CurrentDemandRes WeldingDetectionRes} / DC_EVSEStatus / EVSENotif StopCharging</li> </ul>	usCode / DC_EVSEStatus: EVSEStatusCode: EVSE_Shutdown EVSENotification: 5, StopCharging	Ρ
f	EVSE r (optiona	eal time available load current al)	CurrentDemandRes/EVSEMaximumCurrentLimit		N/A



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Clause	Requirement + Test		Result - Remark	Verdict
g	Loss of digital communication	Message timers Control pilot state	Message timers accord with the requirments in DIN 70121 After direct change of pilot from state C to state A, the output current can be less than 5 A within 30 ms and De-energization of the system can be done within 100 ms.	Ρ
h-1	Zero current confirmed	PowerDeliveryRes/ResponseCode CurrentDemandRes/EVSEPresentCu	urrent PowerDeliveryRes: ResponseCode: OK CurrentDemandRes: EVSEPresentCurrent: Multiplier: -1 Unit: A Value: 20	Ρ



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Clause	Requirement + Test		Result - Remark	Verdict
n-2 Weldi	ing detection	WeldingDetection{Req, Res}	DC_EV EVRead EVErroi NO_ER EVRES Welding Respon DC_EV EVSEIs Valid EVSES EVSE_ Notifica EVSEN	dy:true rCode: ROR SSOC: 50 gDetectionRes: hseCode: OK 'SEStatus: solationStatus: P StatusCode: NotReady tionMaxDelay: 0 lotification: None PresentVoltage: er: -1

--- End of Report ---